

Jiaoyang Li

Curriculum Vitae

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Current Appointment

2022-present Assistant Professor, **Robotics Institute, Carnegie Mellon University, USA.**

Education

2017-2022 **Ph.D. in Computer Science**, *University of Southern California (USC)*, Los Angeles, CA, USA.

2013-2017 **B.Eng. in Automation**, *Tsinghua University*, Beijing, China.

Research Interests

I am interested in many topics related to artificial intelligence, multi-agent/robot systems, and optimization, such as automated planning, combinatorial search and optimization, heuristic search, constraint reasoning, and machine learning. My current research focuses on multi-agent planning and coordination.

Research Experience

2017-2022 Research Assistant, **University of Southern California, USA.**
- Advisor: Sven Koenig, Department of Computer Science.
02/2020 Visiting Researcher (11 months), **Monash University, Australia.**
- Advisor: Daniel Harabor and Peter J. Stuckey, Faculty of Information Technology.
05/2019 Research Intern (14 weeks), **Amazon Robotics, USA.**
- Mentor: Andrew Tinka; Supervisor: Joseph W. Durham.
12/2018, Visiting Student (twice, 5 weeks in total), **Ben-Gurion University, Israel.**
11/2019 - Advisor: Ariel Felner, Department of Software and Information Systems Engineering.
08/2016 Visiting Student (5 weeks), **University of California, Berkeley, USA.**
- Advisor: Zuojun (Max) Shen, Department of Industrial Engineering and Operations Research.
06/2016 Visiting Student (6 weeks), **University of Southern California, USA.**
- Advisor: Sven Koenig, Department of Computer Science.

Honors and Awards

2021 Selected Participant for Rising Stars: An Academic Career Workshop in EECS, *MIT.*
2021 Best System Demonstration Award, *International Conference on Automated Planning and Scheduling.*
2021 WiSE Merit Award for Doctoral Students (4 recipients in Viterbi School of Engineering), *USC.*
2021 Best Research Assistant Award (2 recipients in Computer Science Department), *USC.*
2020 Winner Team (team leader) of both rounds of the Flatland Challenge: NeurIPS Competition on Multi-Agent Reinforcement Learning on Trains (>700 participants with >2000 submissions over 4 months).
2020 Outstanding Student Paper Award, *International Conference on Automated Planning and Scheduling.*
2020 WiSE Qualcomm Top-Off Fellowship (8 recipients in Viterbi School of Engineering), *USC.*
2018 Technology Commercialization Award, *USC.*
2017 Viterbi/Graduate School Fellowship, *USC.*
2017 Excellent Graduate Award of Beijing, *Beijing Municipal Education Commission.*
2017 Excellent Graduate Award of Department of Automation, *Tsinghua.*
2015 Fellowship of Spark Talents Program (50 recipients in Tsinghua), *Tsinghua.*
2015 "12.9" Scholarship (1 recipient in Department of Automation), *Tsinghua.*
2015 Weimin Zheng Scholarship (2 recipients in Department of Automation), *Tsinghua.*

Publications

Conferences

- 2022 [C40] **Multi-Goal Multi-Agent Pickup and Delivery.**
Qinghong Xu, Jiaoyang Li, Sven Koenig and Hang Ma.
IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS**), (in print), 2022.
- [C39] **A MIP-Based Approach for Multi-Robot Geometric Task-and-Motion Planning.**
Hejia Zhang, Shao-Hung Chan, Jie Zhong, Jiaoyang Li, Sven Koenig and Stefanos Nikolaidis.
IEEE International Conference on Automation Science and Engineering (**CASE**), (in print), 2022.
- [C38] **Which MAPF Model Works Best for Automated Warehousing?**
Sumanth Varambally, Jiaoyang Li and Sven Koenig.
Symposium on Combinatorial Search (**SoCS**), (in print), 2022.
Acceptance rate: $31/79 = 39.2\%$.
- [C37] **Learning a Priority Ordering for Prioritized Planning in Multi-Agent Path Finding.**
Shuyang Zhang, Jiaoyang Li, Taoan Huang, Sven Koenig and Bistra Dilikina.
Symposium on Combinatorial Search (**SoCS**), (in print), 2022.
Acceptance rate: $31/79 = 39.2\%$.
- [C36] **Multi-Train Path Finding Revisited.**
Zhe Chen, Jiaoyang Li, Daniel Harabor, Peter Stuckey and Sven Koenig.
Symposium on Combinatorial Search (**SoCS**), (in print), 2022.
Acceptance rate: $31/79 = 39.2\%$.
- [C35] **Mutex Propagation in Multi-Agent Path Finding for Large Agents** (short paper).
Han Zhang, Yutong Li, Jiaoyang Li, T. K. Satish Kumar and Sven Koenig.
Symposium on Combinatorial Search (**SoCS**), (in print), 2022.
Acceptance rate: $31/79 = 39.2\%$.
- [C34] **Optimal and Bounded-Suboptimal Multi-Goal Task Assignment and Path Finding.**
Xinyi Zhong, Jiaoyang Li, Sven Koenig and Hang Ma.
IEEE International Conference on Robotics and Automation (**ICRA**), (in print), 2022.
- [C33] **Multi-Agent Path Finding for Precedence-Constrained Goal Sequences.**
Han Zhang*, Jingkai Chen*, Jiaoyang Li, Brian C. Williams and Sven Koenig.
International Joint Conference on Autonomous Agents and Multiagent Systems (**AAMAS**), pages 1464-1472, 2022.
Acceptance rate: $166/629 = 26.4\%$.
- [C32] **MAPF-LNS2: Repairing Multi-Agent Path Finding via Large Neighborhood Search.**
Jiaoyang Li, Zhe Chen, Daniel Harabor, Peter J. Stuckey and Sven Koenig.
AAAI Conference on Artificial Intelligence (**AAAI**), (in print), 2022.
Acceptance rate: $1,349/9,251 = 14.9\%$.
- [C31] **Anytime Multi-Agent Path Finding via Machine Learning-Guided Large Neighborhood Search.**
Taoan Huang, Jiaoyang Li, Sven Koenig and Bistra Dilikina.
AAAI Conference on Artificial Intelligence (**AAAI**), (in print), 2022.
Acceptance rate: $1,349/9,251 = 14.9\%$.
- [C30] **Shard Systems: Scalable, Robust and Persistent Multi-Agent Path Finding with Performance Guarantees.**
Christopher Leet, Jiaoyang Li and Sven Koenig.
AAAI Conference on Artificial Intelligence (**AAAI**), (in print), 2022.
Acceptance rate: $1,349/9,251 = 14.9\%$.
- [C29] **Flex Distribution for Bounded-Suboptimal Multi-Agent Path Finding.**
Shao-Hung Chan, Jiaoyang Li, Graeme Gange, Daniel Harabor, Peter J. Stuckey and Sven Koenig.
AAAI Conference on Artificial Intelligence (**AAAI**), (in print), 2022.
Acceptance rate: $1,349/9,251 = 14.9\%$.
- 2021 [C28] **Anytime Multi-Agent Path Finding via Large Neighborhood Search.**
Jiaoyang Li, Zhe Chen, Daniel Harabor, Peter J. Stuckey and Sven Koenig.
International Joint Conference on Artificial Intelligence (**IJCAI**), pages 4127-4135, 2021.
Acceptance rate: $587/4204 = 13.9\%$.

- [C27] **Scalable Rail Planning and Replanning: Winning the 2020 Flatland Challenge.** [Winner of the Flatland Challenge at NeurIPS'20.](#)
Jiaoyang Li, Zhe Chen, Yi Zheng, Shao-Hung Chan, Daniel Harabor, Peter J. Stuckey, Hang Ma and Sven Koenig.
 International Conference on Automated Planning and Scheduling (**ICAPS**), pages 477-485, 2021.
- [C26] **Conflict-Based Increasing Cost Search.**
 Thayne T. Walker, Nathan R. Sturtevant, Han Zhang, **Jiaoyang Li**, Ariel Felner and T. K. Satish Kumar.
 International Conference on Automated Planning and Scheduling (**ICAPS**), pages 385-395, 2021.
- [C25] **EECBS: Bounded-Suboptimal Search for Multi-Agent Path Finding.**
Jiaoyang Li, Wheeler Ruml and Sven Koenig.
 AAAI Conference on Artificial Intelligence (**AAAI**), pages 12353-12362, 2021.
 Acceptance rate: $1692/7911 = 21.4\%$.
- [C24] **Lifelong Multi-Agent Path Finding in Large-Scale Warehouses.**
Jiaoyang Li, Andrew Tinka, Scott Kiesel, Joseph W. Durham, T. K. Satish Kumar and Sven Koenig.
 AAAI Conference on Artificial Intelligence (**AAAI**), pages 11272-11281, 2021.
 Acceptance rate: $1692/7911 = 21.4\%$.
- [C23] **Scalable and Safe Multi-Agent Motion Planning with Nonlinear Dynamics and Bounded Disturbances.**
 Jingkai Chen, **Jiaoyang Li**, Chuchu Fan and Brian Williams.
 AAAI Conference on Artificial Intelligence (**AAAI**), pages 11237-11245, 2021.
 Acceptance rate: $1692/7911 = 21.4\%$.
- [C22] **Symmetry Breaking for k-Robust Multi-Agent Path Finding.**
 Zhe Chen, Daniel Harabor, **Jiaoyang Li** and Peter J. Stuckey.
 AAAI Conference on Artificial Intelligence (**AAAI**), pages 12267-12274, 2021.
 Acceptance rate: $1692/7911 = 21.4\%$.
- 2020 [C21] **Flatland Competition 2020: MAPF and MARL for Efficient Train Coordination on a Grid World.**
 Florian Laurent, Manuel Schneider, Christian Scheller, Jeremy Watson, **Jiaoyang Li**, Zhe Chen, Yi Zheng, Shao-Hung Chan, Konstantin Makhnev, Oleg Svidchenko, Vladimir Egorov, Dmitry Ivanov, Aleksei Shpilman, Evgenija Spirovska, Oliver Tanevski, Aleksandar Nikov, Ramon Grunder, David Galevski, Jakov Mitrovski, Guillaume Sartoretti, Zhiyao Luo, Mehul Damani, Nilabha Bhattacharya, Shivam Agarwal, Adrian Egli, Erik Nygren and Sharada Mohanty.
 NeurIPS 2020 Competition and Demonstration Track, Proceedings of Machine Learning Research (**PMLR**), volume 133, pages 275-301, 2020.
- [C20] **Mutex Propagation for SAT-Based Multi-Agent Path Finding.**
 Pavel Surynek, **Jiaoyang Li**, Han Zhang, T. K. Satish Kumar and Sven Koenig.
 International Conference on Principles and Practice of Multi-Agent Systems (**PRIMA**), 2020.
 Acceptance rate: $19/50 = 38.0\%$.
- [C19] **Multi-Directional Heuristic Search.**
 Dor Atzmon, **Jiaoyang Li**, Ariel Felner, Eliran Nachmani, Shahaf Shperberg, Nathan R. Sturtevant and Sven Koenig.
 International Joint Conference on Artificial Intelligence (**IJCAI**), pages 4062-4068, 2020.
 Acceptance rate: $592/4717 = 12.6\%$.
- [C18] **Iterative-Deepening Conflict-Based Search.**
 Eli Boyarski, Ariel Felner, Daniel Harabor, Peter J. Stuckey, Liron Cohen, **Jiaoyang Li** and Sven Koenig.
 International Joint Conference on Artificial Intelligence (**IJCAI**), pages 4084-4090, 2020.
 Acceptance rate: $592/4717 = 12.6\%$.
- [C17] **New Techniques for Pairwise Symmetry Breaking in Multi-Agent Path Finding.**
Jiaoyang Li, Graeme Gange, Daniel Harabor, Peter J. Stuckey, Hang Ma and Sven Koenig.
 International Conference on Automated Planning and Scheduling (**ICAPS**), pages 193-201, 2020.
 Acceptance rate: $69/216 = 31.9\%$.
- [C16] **Multi-Agent Pathfinding with Mutex Propagation.** [Outstanding Student Paper Award.](#)
 Han Zhang, **Jiaoyang Li**, Pavel Surynek, Sven Koenig and T. K. Satish Kumar.
 International Conference on Automated Planning and Scheduling (**ICAPS**), pages 323-332, 2020.
 Acceptance rate: $69/216 = 31.9\%$.

- [C15] **Moving Agents in Formation in Congested Environments.**
Jiaoyang Li, Kexuan Sun, Hang Ma, Ariel Felner, T. K. Satish Kumar and Sven Koenig.
 International Joint Conference on Autonomous Agents and Multiagent Systems (**AAMAS**), pages 726-734, 2020.
 Acceptance rate: $186/808 = 23.0\%$.
- [C14] **Model AI Assignments 2020.**
 Todd W.Neller, Stephen Keeley, Michael Guerzhoy, Wolfgang Hoenig, Jiaoyang Li, Sven Koenig, Ameet Soni, Krista Thomason, Lisa Zhang, Bibin Sebastian, Cinjon Resnick, Avital Oliver, Surya Bhupatiraju, Kumar Krishna Agrawal, James Allingham, Sejong Yoon, Johnathan Chen, Tom Larsen, Marion Neumann, Narges Norouzi, Ryan Hausen and Matthew Evett.
 Symposium on Educational Advances in Artificial Intelligence (**EAAI**), 2020.
- 2019 [C13] **Scheduling and Airport Taxiway Path Planning under Uncertainty.**
Jiaoyang Li, Han Zhang, Mimi Gong, Zi Liang, Weizi Liu, Zhongyi Tong, Liangchen Yi, Robert Morris, Corina Pasareanu and Sven Koenig.
 AIAA Aviation and Aeronautics Forum and Exposition (**AIAA AVIATION Forum**), 2019.
- [C12] **Multi-Agent Pathfinding: Definitions, Variants, and Benchmarks** (position paper).
 Roni Stern, Nathan R. Sturtevant, Ariel Felner, Sven Koenig, Hang Ma, Thayne T. Walker, Jiaoyang Li, Dor Atzmon, Liron Cohen, T. K. Satish Kumar, Eli Boyarski and Roman Bartak.
 Symposium on Combinatorial Search (**SoCS**), pages 151-159, 2019.
 Acceptance rate: $14/31 = 45.2\%$.
- [C11] **Improved Heuristics for Conflict-Based Search for Multi-Agent Path Finding.**
Jiaoyang Li, Eli Boyarski, Ariel Felner, Hang Ma and Sven Koenig.
 International Joint Conference on Artificial Intelligence (**IJCAI**), pages 442-449, 2019.
 Acceptance rate: $850/4752 = 17.9\%$.
- [C10] **Using FastMap to Solve Graph Problems in a Euclidean Space** (short paper).
Jiaoyang Li, Ariel Felner, Sven Koenig and T. K. Satish Kumar.
 International Conference on Automated Planning and Scheduling (**ICAPS**), pages 273-278, 2019.
- [C9] **Disjoint Splitting for Multi-Agent Path Finding with Conflict-Based Search** (short paper).
Jiaoyang Li, Daniel Harabor, Peter J. Stuckey, Ariel Felner, Hang Ma and Sven Koenig.
 International Conference on Automated Planning and Scheduling (**ICAPS**), pages 279-283, 2019.
- [C8] **Task and Path Planning for Multi-Agent Pickup and Delivery.**
 Minghua Liu, Hang Ma, Jiaoyang Li and Sven Koenig.
 International Joint Conference on Autonomous Agents and Multiagent Systems (**AAMAS**), pages 1152-1160, 2019.
 Acceptance rate: $189/781 = 24.2\%$.
- [C7] **Multi-Agent Path Finding for Large Agents.**
Jiaoyang Li, Pavel Surynek, Ariel Felner, Hang Ma, T. K. Satish Kumar and Sven Koenig.
 AAAI Conference on Artificial Intelligence (**AAAI**), pages 7627-7634, 2019.
 Acceptance rate: $1150/7095 = 16.2\%$.
- [C6] **Symmetry Breaking Constraints for Grid-Based Multi-Agent Path Finding.**
Jiaoyang Li, Daniel Harabor, Peter J. Stuckey, Hang Ma and Sven Koenig.
 AAAI Conference on Artificial Intelligence (**AAAI**), pages 6087-6095, 2019.
 Acceptance rate: $1150/7095 = 16.2\%$.
- [C5] **Searching with Consistent Prioritization for Multi-Agent Path Finding.**
 Hang Ma, Daniel Harabor, Peter J. Stuckey, Jiaoyang Li and Sven Koenig.
 AAAI Conference on Artificial Intelligence (**AAAI**), pages 7643-7650, 2019.
 Acceptance rate: $1150/7095 = 16.2\%$.
- 2018 [C4] **Adding Heuristics to Conflict-Based Search for Multi-Agent Path Finding** (short paper).
 Ariel Felner, Jiaoyang Li, Eli Boyarski, Hang Ma, Liron Cohen, T. K. Satish Kumar and Sven Koenig.
 International Conference on Automated Planning and Scheduling (**ICAPS**), pages 83-87, 2018.
 Acceptance rate: $69/209 = 33.0\%$.
- [C3] **Multi-Agent Path Finding with Deadlines.**
 Hang Ma, G. Wagner, Ariel Felner, Jiaoyang Li, T. K. Satish Kumar and Sven Koenig.
 International Joint Conference on Artificial Intelligence (**IJCAI**), pages 417-423, 2018.
 Acceptance rate: $710/3470 = 20.5\%$.

2017 [C2] **Lifelong Multi-Agent Path Finding for Online Pickup and Delivery Tasks.**
Hang Ma, [Jiaoyang Li](#), T. K. Satish Kumar and Sven Koenig.
International Joint Conference on Autonomous Agents and Multiagent Systems (**AAMAS**), pages 837-845, 2017.
Acceptance rate: $155/595 = 26.1\%$.

[C1] **Planning for Electric Taxi Charging System from the Perspective of Transport Energy Supply Chain: A Data-Driven Approach in Beijing.**
Yinghao Jia, Huimiao Chen, [Jiaoyang Li](#), Fang He, Meng Li, Zechun Hu and Zuo-Jun Max Shen.
IEEE Transportation Electrification Conference & EXPO Asia-Pacific (**ITEC-AP**), pages 1-6, 2017.

Journals

2022 [J3] **Multi-Agent Path Finding with Mutex Propagation.**
Han Zhang, Pavel Surynek, [Jiaoyang Li](#), T. K. Satish Kumar and Sven Koenig.
Artificial Intelligence, (in print), 2022.

2021 [J2] **Pairwise Symmetry Reasoning for Multi-Agent Path Finding Search.**
[Jiaoyang Li](#), Daniel Harabor, Peter J. Stuckey, Hang Ma, Graeme Gange and Sven Koenig.
Artificial Intelligence, volume 301, 2021.

2017 [J1] **Optimal Combinations and Variable Departure Intervals for Micro Bus System.**
[Jiaoyang Li](#), Jianming Hu and Yi Zhang.
Tsinghua Science and Technology (**TST**), 22(3):282-292, 2017.

Book Chapters

2021 [B1] **Artificial Intelligence and Automation.**
Sven Koenig, Shao-Hung Chan, [Jiaoyang Li](#) and Yi Zheng.
In Handbook of Automation, Shimon Y. Nof (editor), Springer, 2021.

Workshops

Workshop papers with a conference version are not listed below.

2022 [W3] **Deadline-Aware Multi-Agent Tour Planning.**
Taoan Huang, Vikas Shivashankar, Michael Caldara, Joseph Durham, [Jiaoyang Li](#), Bistra Dilkina and Sven Koenig.
IJCAI Workshop on Heuristic Search in Industry (**HSI**), 2022.

2021 [W2] **A Hierarchical Approach to Multi-Agent Path Finding.**
Han Zhang, Mingze Yao, Ziang Liu, [Jiaoyang Li](#), Lucas Terr, Shao-Hung Chan, T. K. Satish Kumar and Sven Koenig.
ICAPS Workshop on Hierarchical Planning (**HPLAN**), 2021.

2020 [W1] **Nested ECBS for Bounded Suboptimal Multi-Agent Path Finding.**
Shao-Hung Chan, [Jiaoyang Li](#), Daniel Harabor, Peter J. Stuckey, Graeme Gange, Liron Cohen and Sven Koenig.
IJCAI Workshop on Multi-Agent Path Finding (**WoMAPF**), 2020.

Demos

2021 [D1] **Scalable Rail Planning and Replanning: Winning the 2020 Flatland Challenge.** [Best System Demonstration Award.](#)
[Jiaoyang Li](#), Zhe Chen, Yi Zheng, Shao-Hung Chan, Daniel Harabor, Peter J. Stuckey, Hang Ma and Sven Koenig.
System Demonstrations and Exhibits Program at International Conference on Automated Planning and Scheduling (**ICAPS**), 2021.

Extended Abstracts

Extended abstracts with a conference or workshop version are not listed below.

2019 [E1] **A New Constraint Satisfaction Perspective on Multi-Agent Path Finding: Preliminary Results** (extended abstract).
Jiangxing Wang, [Jiaoyang Li](#), Hang Ma, Sven Koenig and T. K. Satish Kumar.
International Joint Conference on Autonomous Agents and Multiagent Systems (**AAMAS**), pages 2253-2255, 2019.
Acceptance rate: $407/781=52.1\%$.

Media Coverage

- 03/2021 Making the (Virtual) Trains Run On Time: USC Team World Champs in AI Challenge, USC Press
- 05/2020 Amazon Studies Anti-Collision Method for Robots to Increase Throughput, Supply Chain Dive
- 05/2020 Amazon's AI Tool Can Plan Collision-Free Paths for 1,000 Warehouse Robots, Venture Beat
- Also distributed via ACM TechNews.

Teaching and Mentoring Experience

Teaching

- Summer 2021 Research Coach at Viterbi Summer Institute (VSI). USC
 - o A program designed to enhance the transition of engineering students from underrepresented backgrounds to USC.
- Spring 2021 Teaching Assistant at Advanced Analysis of Algorithms, CSCI670 (graduate level). USC
- Fall 2019 Teaching Assistant at Introduction to Artificial Intelligence, CSCI360 (undergraduate level). USC
- Summer 2019 Lab Assistant at the Third Summer School on Cognitive Robotics. USC
 - o Co-developed a lab project on multi-agent path finding, which was later chosen as a [Model AI Assignment 2020](#) by the Symposium on Educational Advances in Artificial Intelligence.

Mentoring

- 2021-2022 Sumanth Varambally (Undergraduate Student at Indian Institute of Technology Delhi), *IUSSTF-Viterbi Summer Research Program*.
 - o His paper was published at [SoCS'22](#).
- 2021-2022 Shuyang Zhang (Undergraduate Student at USC), *Center for Undergraduate Research in Viterbi Engineering (CURVE) Program*.
 - o Her poster was selected as a [winner of the CURVE Symposium](#) at USC.
 - o She won a [Best Research Award](#) in Computer Science at USC.
 - o Her paper was published at [SoCS'22](#).
- Summer 2021 Zhiqian Zhou (Undergraduate Student at Tsinghua University), *USC-Tsinghua Summer Research Program*.
- 2021 Qinghong Xu (Master's Student at Simon Fraser University).
 - o Her paper was published at [IROS'22](#).
- 2020-2021 Xinyi Zhong (Master's Student at Simon Fraser University).
 - o Her paper was published at [ICRA'22](#).
- 2020-2021 Eugene (Zijun) Lin (Master's Student in Computer Science at USC).
- Fall 2020 Wooju Yim (Undergraduate Student at USC).
- Fall 2020 Leon Durrenberger (Undergraduate Student at USC), *Directed Research Project*.
- Fall 2019 Moli Yang (Master's Student at Melbourne University), *Visiting student*.
- 2018 Jiangxing Wang (Master's Student at USC), *Directed Research Project*.
 - o He won a [Best Research Award](#) in Computer Science at USC.
 - o His paper was published at [AAMAS, 2019](#).
- Summer 2018 Minghua Liu (Undergraduate Student at Tsinghua University), *USC-Tsinghua Summer Research Program*.
 - o His paper was published at [AAMAS, 2019](#).

Academic Activities

Conference and Workshop Organizing Committee

- 2023 Doctoral Consortium Chair at Symposium of Combinatorial Search (SoCS)
- 2022 Co-chair at AAMAS Workshop on Optimization and Learning in Multi-Agent Systems (OptLearnMAS)
- 2022 Local organizing committee at International Conference on the Integration of Constraint Programming, Artificial Intelligence, and Operations Research (CPAIOR)
- 2020 Co-chair at IJCAI Workshop on Multi-Agent Path Finding (WoMAPF)

Conference and Workshop (Senior) Program Committee

- 2022 PC at International Conference on the Integration of Constraint Programming, Artificial Intelligence, and Operations Research (CPAIOR)
- 2021, 2022 PC at AAAI Conference on Artificial Intelligence (AAAI)

- 2021, 2022 PC of the special track on Autonomous Robots and Agents at International Conference of the Florida Artificial Intelligence Research Society (FLAIRS)
- 2021, 2022 PC at International Conference on Automated Planning and Scheduling (ICAPS)
- 2021 PC of the system demonstrations track at International Conference on Automated Planning and Scheduling (ICAPS)
- 2020-2022 PC and Senior PC at International Joint Conference on Artificial Intelligence (IJCAI)
- 2019, 2020 PC at International Conference on Autonomic and Autonomous Systems (ICAS)
- 2019 PC at IJCAI Workshop on Multi-Agent Path Finding (WoMAPF)

Conference and Workshop Reviewer (of Individual Papers)

- 2021, 2022 2x IEEE International Conference on Robotics and Automation (ICRA)
- 2021 2x IEEE International Symposium on Multi-Robot and Multi-Agent Systems (MRS)
- 2021 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
- 2021 Undergraduate Consortium at AAAI Conference on Artificial Intelligence (AAAI-UC)
- 2018-2021 3x AAAI/ACM Conference on Artificial Intelligence, Ethics, and Society (AIES)
- 2020 Workshop on the Algorithmic Foundations of Robotics (WAFR)
- 2019 Global Conference on Artificial Intelligence (GCAI)
- 2019 International Joint Conference on Artificial Intelligence (IJCAI)
- 2019 International Conference on Automated Planning and Scheduling (ICAPS)
- 2019 International Joint Conference on Autonomous Agents and Multiagent Systems (AAMAS)
- 2018, 2019 International Symposium on Combinatorial Search (SoCS)
- 2018 AAAI Conference on Artificial Intelligence and Interactive Digital Entertainment (AIIDE)
- 2018 ACM Siggraph Conference on Motion, Interaction and Games (MIG)
- 2018 IEEE Conference on Computational Intelligence and Games (CIG)
- 2018 ICAPS Workshop on Planning and Robotics (PlanRob)

Journal Reviewer

- 2022 Autonomous Agents and Multi-Agent Systems (JAAMAS)
- 2022 IEEE Transactions on Robotics (T-RO)
- 2021, 2022 3x Artificial Intelligence (AIJ)
- 2019-2022 5x IEEE Robotics and Automation Letters (RA-L)
- 2021 Journal of Artificial Intelligence Research (JAIR)
- 2020, 2021 IEEE Transactions on Automation Science and Engineering (T-ASE)
- 2020 IEEE Transactions on Control of Network Systems (TCNS)
- 2020 Journal of Aerospace Information Systems (JAIS)
- 2020 Aerospace Lab (AL)
- 2017 Tsinghua Science and Technology (TST)

Others

- 2022 Chair of Session (16a) "Multi-Agent Planning" at International Conference on Automated Planning and Scheduling (ICAPS)
- 2021 Mentor of the WiSE PhD Mentorship Program at USC
- 2021 Judge of the Symposium of the Center for Undergraduate Research in Viterbi Engineering (CURVE) Program at USC
- 2021 Invited Panelist of Grad Student Panel at AAAI Undergraduate Consortium
- 2020 Invited Panelist of Flatland Townhall Panel at NeurIPS Competition Track

Talks and Presentations

Invited Talks

- 06/2022 **Intelligent Planning for Large-Scale Multi-Agent Coordination** (virtual). ICAPS'22 Workshop on Heuristics and Search for Domain-independent Planning.

- 03/2022 **Introduction to Multi-Agent Path Finding** (virtual). Guest Lecturer at the MIT Course on Cognitive Robotics.
- 03/2021 **Large Scale Multi-Agent Path Finding** (virtual, in Chinese). AI TIME.
- 10/2019 **Fast and Realistic Multi-Agent Path Finding**. Amazon Research Awards - Robotics Symposium.

Conference Tutorials

- 05/2022 AAMAS tutorial on **Recent Advances in Multi-Agent Path Finding** (with Daniel Harabor, Sven Koenig, and Ariel Felner).
- 02/2022 AAAI tutorial on **Recent Advances in Multi-Agent Path Finding** (with Daniel Harabor, Sven Koenig, and Ariel Felner).

Presentations at Conferences and Symposiums

- 02/2022 **MAPP-LNS2: Repairing Multi-Agent Path Finding via Large Neighborhood Search** (virtual). AAAI Conference on Artificial Intelligence (AAAI).
- 08/2021 **Anytime Multi-Agent Path Finding via Large Neighborhood Search** (virtual). International Joint Conference on Artificial Intelligence (IJCAI).
- 08/2021 **Scalable Rail Planning and Replanning: Winning the 2020 Flatland Challenge** (virtual). International Conference on Automated Planning and Scheduling (ICAPS).
- 02/2021 **EECBS: A Bounded-Suboptimal Search on Multi-Agent Path Finding** (virtual). AAAI Conference on Artificial Intelligence (AAAI).
- 02/2021 **Lifelong Multi-Agent Path Finding in Large-Scale Warehouses** (virtual). AAAI Conference on Artificial Intelligence (AAAI).
- 12/2020 **Winning the 2020 Flatland Challenge** (virtual). Conference on Neural Information Processing Systems (NeurIPS).
- 10/2020 **New Techniques for Pairwise Symmetry Breaking in Multi-Agent Path Finding** (virtual). International Conference on Automated Planning and Scheduling (ICAPS).
- 10/2020 **Pairwise Symmetry Reasoning for Multi-Agent Path Finding** (virtual). Doctoral Consortium at the International Conference on Automated Planning and Scheduling (ICAPS).
- 05/2020 **Moving Agents in Formation in Congested Environments** (virtual). Symposium on Combinatorial Search (SoCS).
- 05/2020 **New Techniques for Pairwise Symmetry Breaking in Multi-Agent Path Finding** (virtual). Symposium on Combinatorial Search (SoCS).
- 05/2020 **Moving Agents in Formation in Congested Environments** (virtual). International Joint Conference on Autonomous Agents and Multiagent Systems (AAMAS).
- 05/2020 **Lifelong Multi-Agent Path Finding in Large-Scale Warehouses** (virtual). International Joint Conference on Autonomous Agents and Multiagent Systems (AAMAS).
- 02/2020 **A Project on Multi-Agent Path Finding**. Educational Advances in Artificial Intelligence (EAAI).
- 08/2019 **Improved Heuristics for Conflict-Based Search for Multi-Agent Path Finding**. International Joint Conference on Artificial Intelligence (IJCAI).
- 08/2019 **Disjoint Splitting for Multi-Agent Path Finding with Conflict-Based Search**. IJCAI-19 Workshop on Multi-Agent Path Finding (WoMAPF).
- 07/2019 **Using FastMap to Solve Graph Problems in a Euclidean Space**. International Conference on Automated Planning and Scheduling (ICAPS).
- 07/2019 **Disjoint Splitting for Multi-Agent Path Finding with Conflict-Based Search**. International Conference on Automated Planning and Scheduling (ICAPS).
- 01/2019 **Multi-Agent Path Finding for Large Agents**. AAAI Conference on Artificial Intelligence (AAAI).
- 01/2019 **Symmetry Breaking Constraints for Grid-Based Multi-Agent Path Finding**. AAAI Conference on Artificial Intelligence (AAAI).