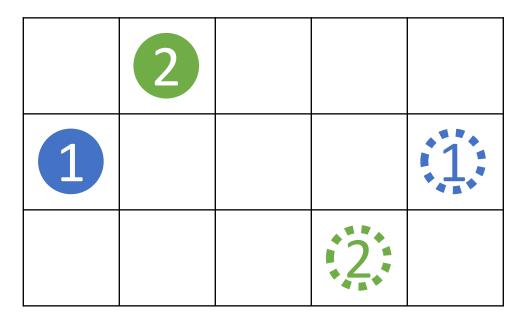


Disjoint Splitting for Multi-Agent Path Finding with Conflict-Based Search

Jiaoyang Li, Daniel Harabor, Peter J. Stuckey, Ariel Felner, Hang Ma, and Sven Koenig Berkeley, CA 07/15/2019

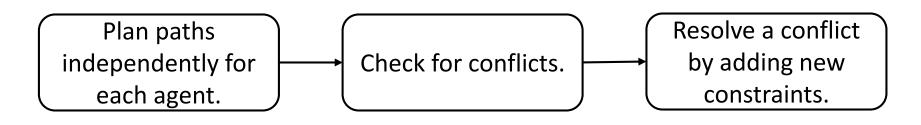


Multi-Agent Path Finding (MAPF)

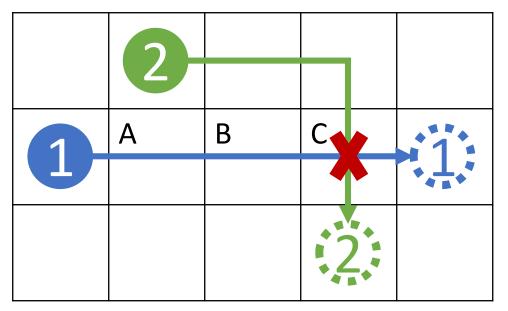


- Goal:
 - Find collision-free paths.
 - Minimize the sum of path costs.
- MAPF is NP-hard to solve optimally.

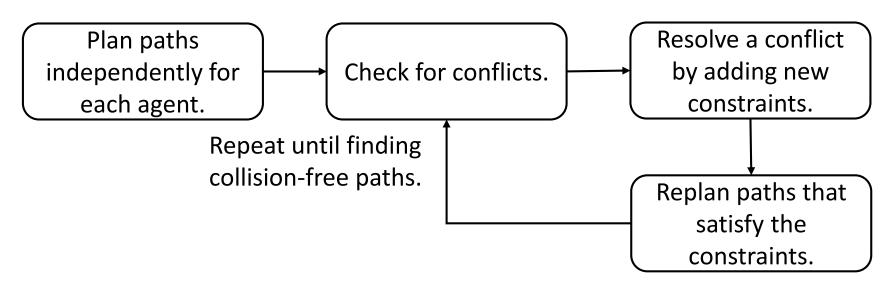
Conflict-Based Search (CBS)



Both agents are at C at time 3.



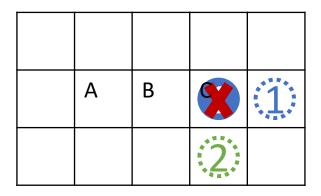
Conflict-Based Search (CBS)



OR

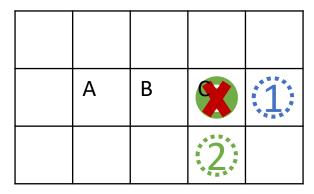
Case 1:

Agent 1 cannot be at C at time 3.



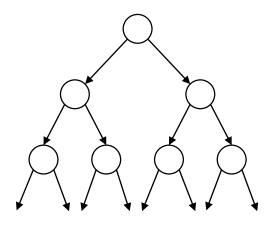
Case 2:

Agent 2 cannot be at C at time 3.



Conflict-Based Search (CBS)

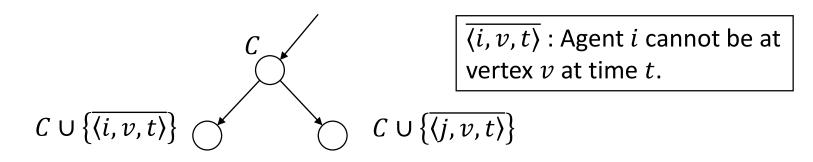
• The high-level of CBS searches in a binary tree using a best-first manner.



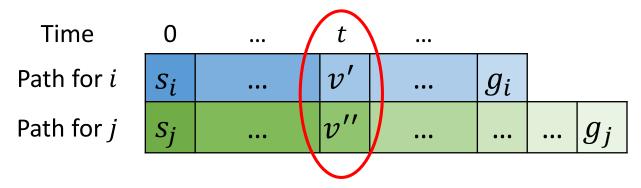
• The low-level of CBS replans paths for single agents.

The splitting of CBS

• To resolve a conflict between agents *i* and *j* at vertex *v* at time *t*:

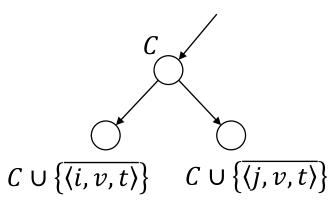


- The searching spaces (i.e., sets of paths that satisfy the constraints) of the two child nodes are **not disjoint**!
 - The following pair of paths satisfies both constraints.



The splitting of CBS

• Non-disjoint splitting:



- Negative constraint $\overline{\langle i, v, t \rangle}$:
 - Agent *i* cannot be at *v* at time *t*.

• Disjoint splitting:

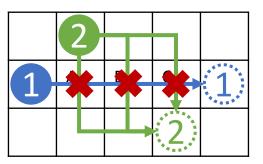
 $C \cup \{\overline{\langle i, v, t \rangle}\}$

- Positive constraint $\langle i, v, t \rangle$:
 - Agent *i* must be at *v* at time *t*.

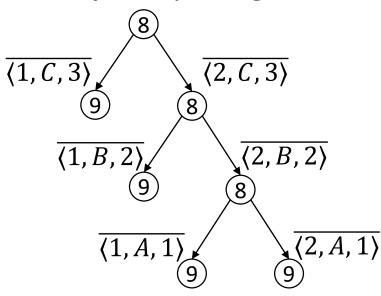
 $C \cup \{\langle i, v, t \rangle\}$

Any other agents (including agent j) cannot be at v at time t.

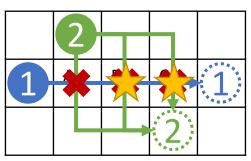
Example

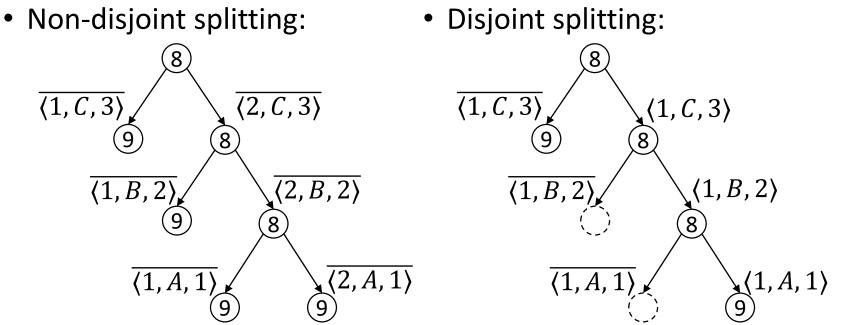


• Non-disjoint splitting:



Example



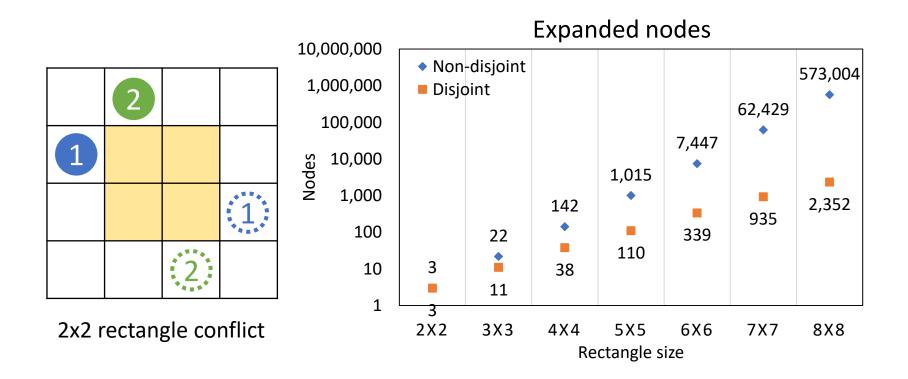


Example С В А **.** • Non-disjoint splitting: **Disjoint splitting:** • 8 8 $\overline{\langle 1, C, 3 \rangle}$ $\overline{\langle 1, C, 3 \rangle}$ $\overline{\langle 2, C, 3 \rangle}$ $\langle 1, C, 3 \rangle$ 8 8 $\langle 1, B, 2 \rangle$ $\overline{\langle 2, B, 2 \rangle}$ $\overline{\langle 1, B, 2 \rangle}$ <u>(1, *B*, 2</u> 9 8 8 $\langle 1, A, 1 \rangle$ $\overline{\langle 2, A, 1 \rangle}$ $\overline{\langle 1, A, 1 \rangle}$ <u>(1, A, 1</u>

Low-level search of CBS

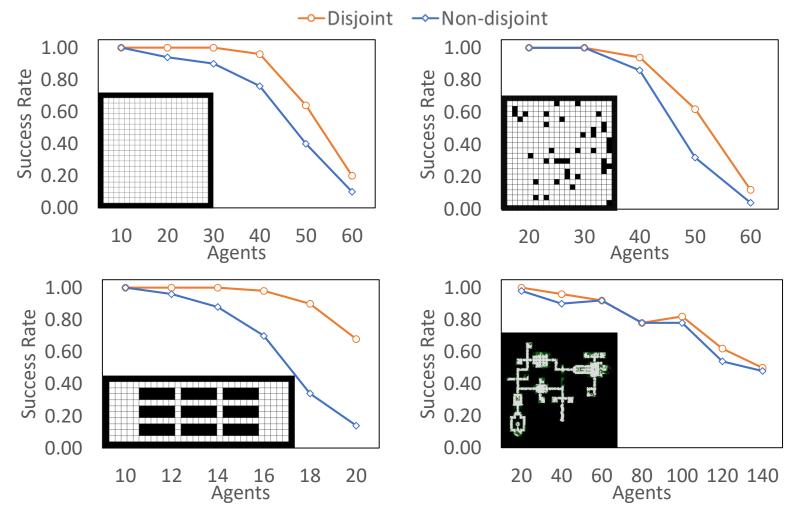
- Non-disjoint splitting
 - Replan the entire path.
- Disjoint splitting
 - Replan the path segment between two positive constraints.

Experiments



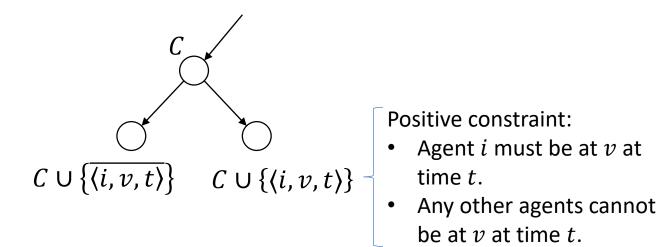
Experiments

Success rate (%solved instances within 5 minutes)



Takeaways

- The splitting of standard CBS is not disjoint.
- Disjoint splitting:



• Empirically, disjoint splitting is at least as good as CBS splitting and significantly speeds up CBS in many cases.